

The background of the slide is a grayscale photograph of an industrial manufacturing environment. It features several robotic arms, including a prominent white KUKA arm in the foreground, working on a production line. The scene is filled with various mechanical components, conveyor belts, and industrial structures, creating a sense of a modern, automated factory.

Sharing of Digital (and Physical) Twins within a Global Research Network

International Approaches, Innovations, Methods and Standards
in Industrial Engineering and Management

AIM Conference in Berlin, Germany

September 2020

Jochen Deuse

RESEARCH AREAS

Collaborative Prototyping Environment

Develop an advanced technical capability and safe environment for prototyping and testing cobotic solutions

Human-Robot Collaboration

Solutions for robots and humans to collaborate on shared work processes or production outputs that are intuitive, effective and safe

Robot Awareness of Humans

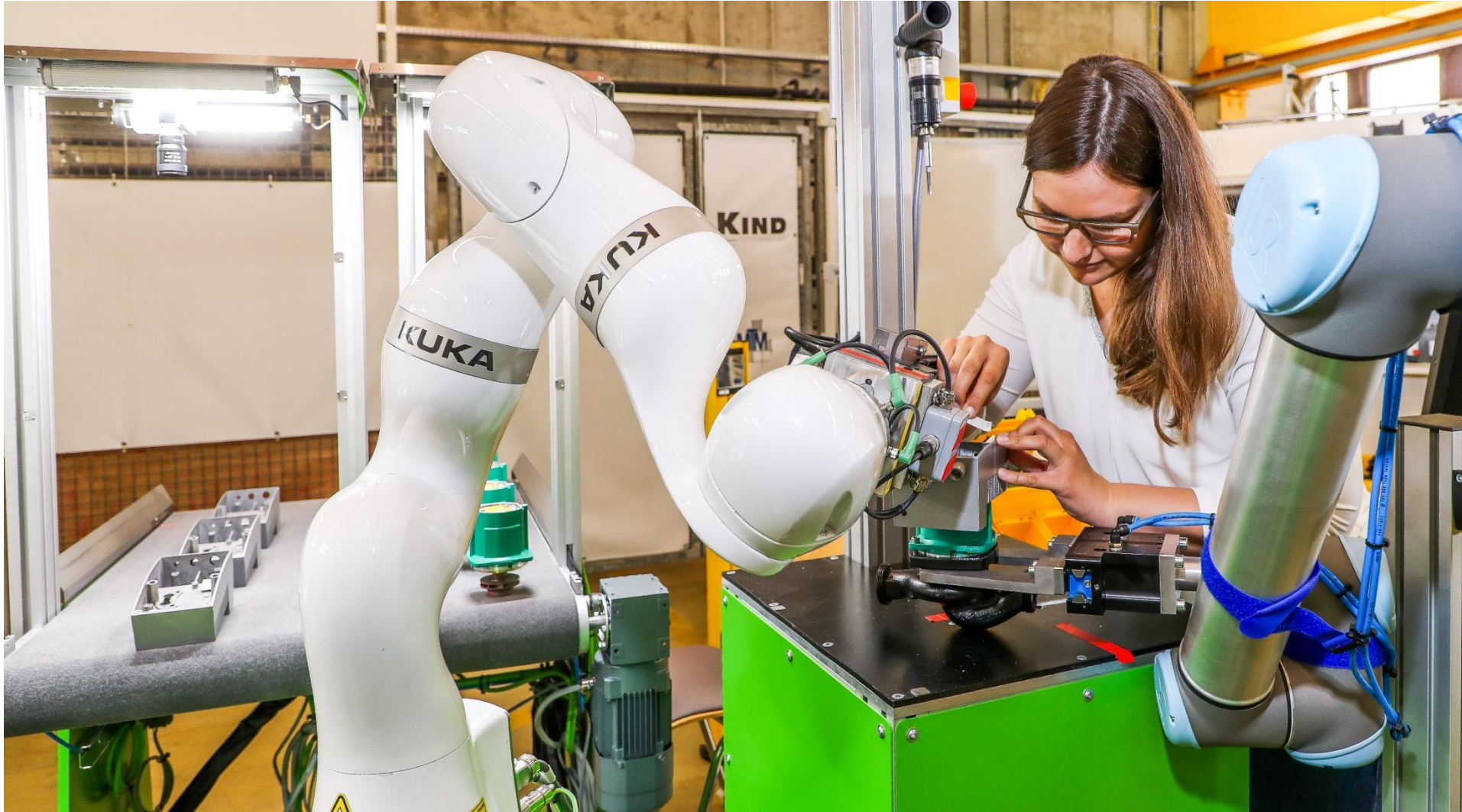
Improve the safety & efficiency of co-locating humans and robotic systems in operational environments

Human Awareness of Robots

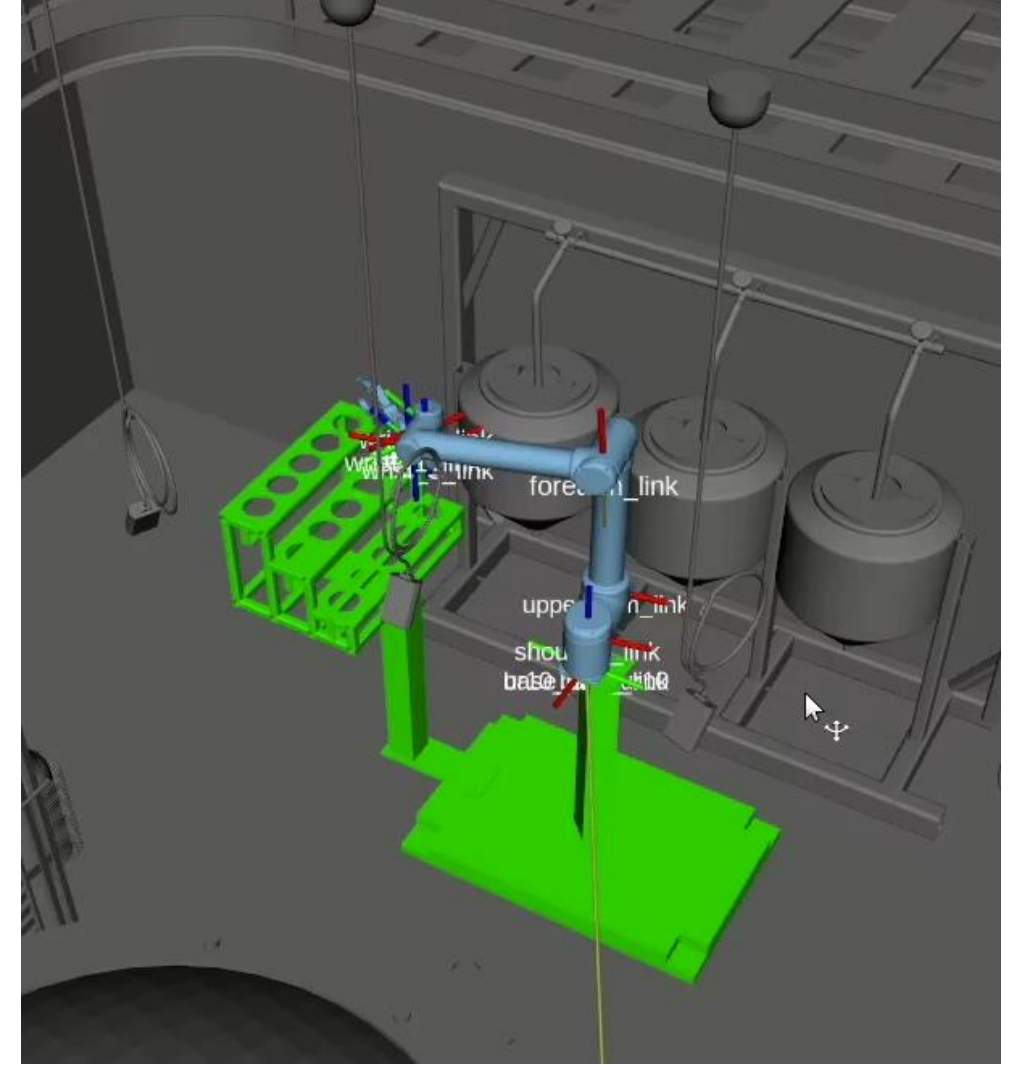
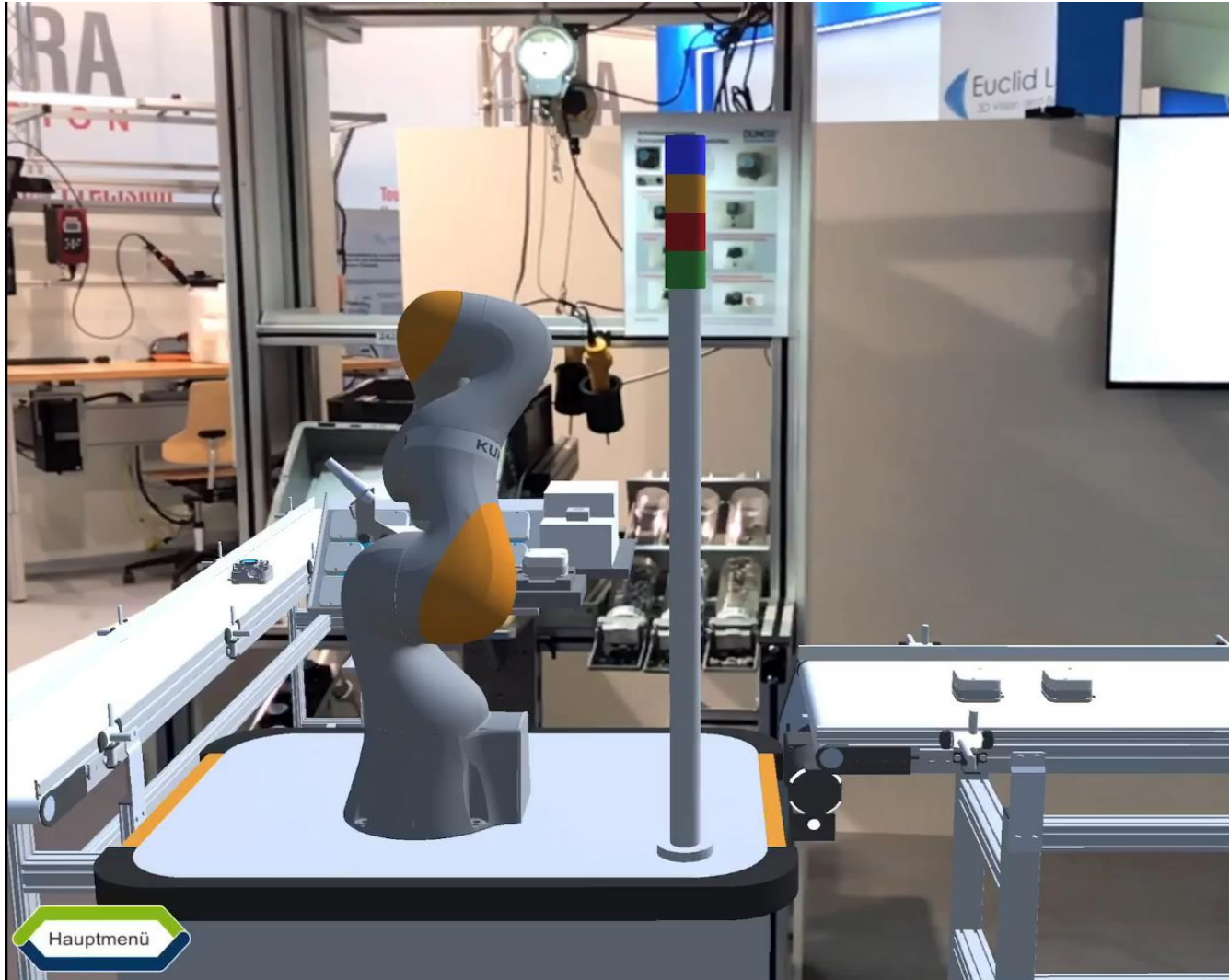
Develop the tasks, indicators, information and processes humans need to work alongside robots

Human-Robot Jobs of the Future

Impact of collaborative robotics on workforce integration, skills development and business adoption and design for human factors in manufacturing industry







Industrielle Demonstrator-Zelle (Bj. 2006, SIM GmbH)

Einsatzzweck:

- Pick & Place-Kreislauf von Wafern
- Randomisierte Platzierung der Wafer auf dem Förderband mit Hilfe eines
- Erkennung der Wafer durch ein Kamerasystem

Steuerung:

- Siemens Simatic S7-300
- Autarke Adept-Steuerung

Komponenten:

1

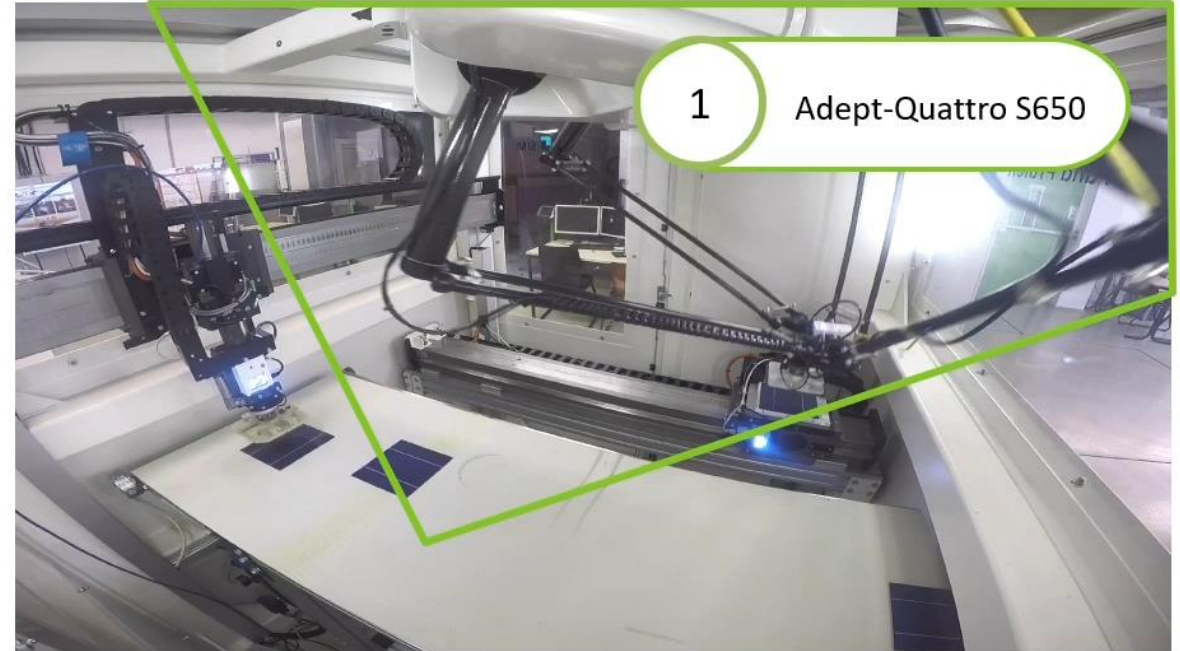
Adept Quattro s650 & pneumatische Greifer mit Adept Sight Vision-System

2

Laterales Lineartransportsystem mit pneumatischen Schunk-Greifer-Modulen

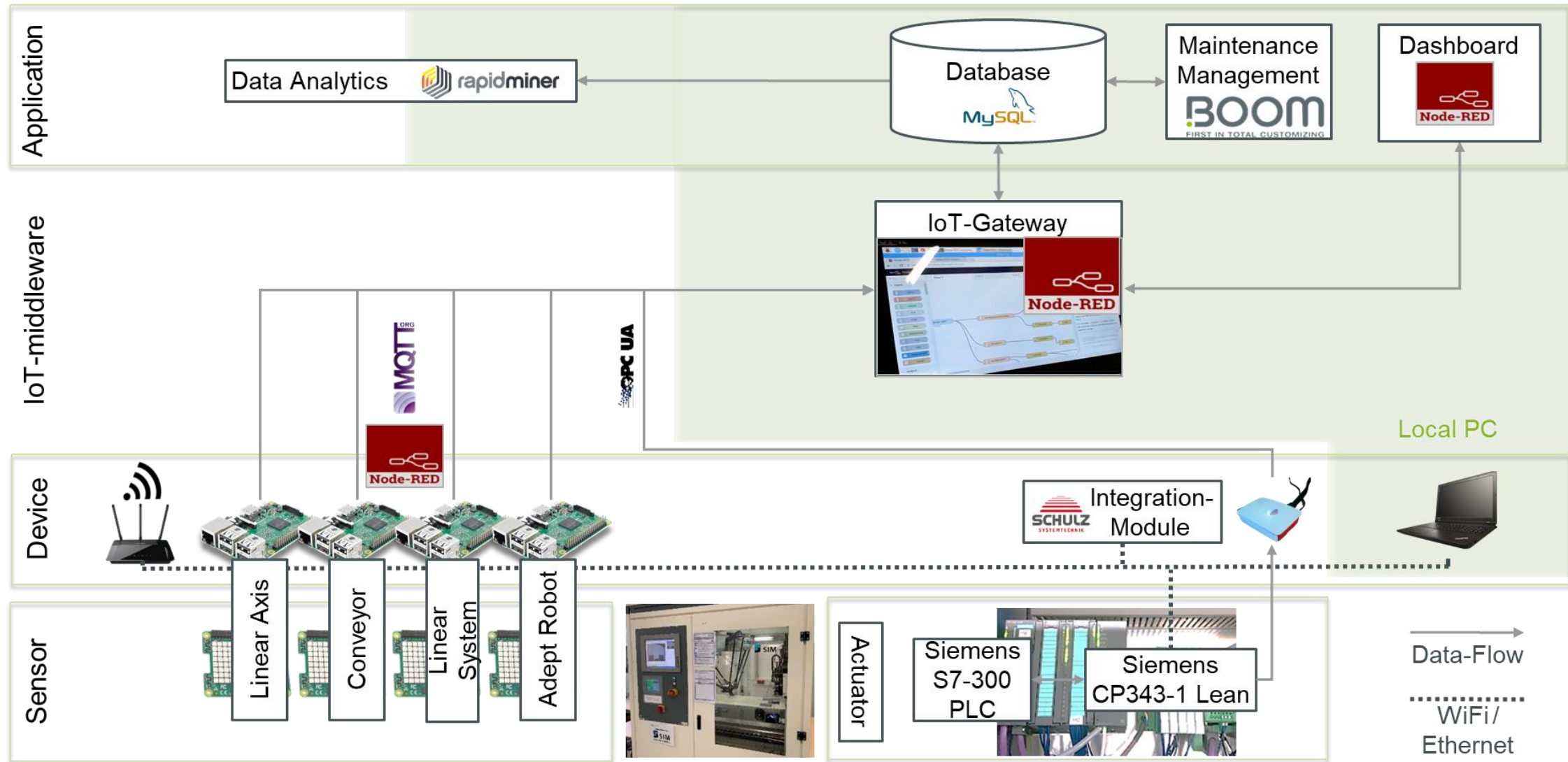
3

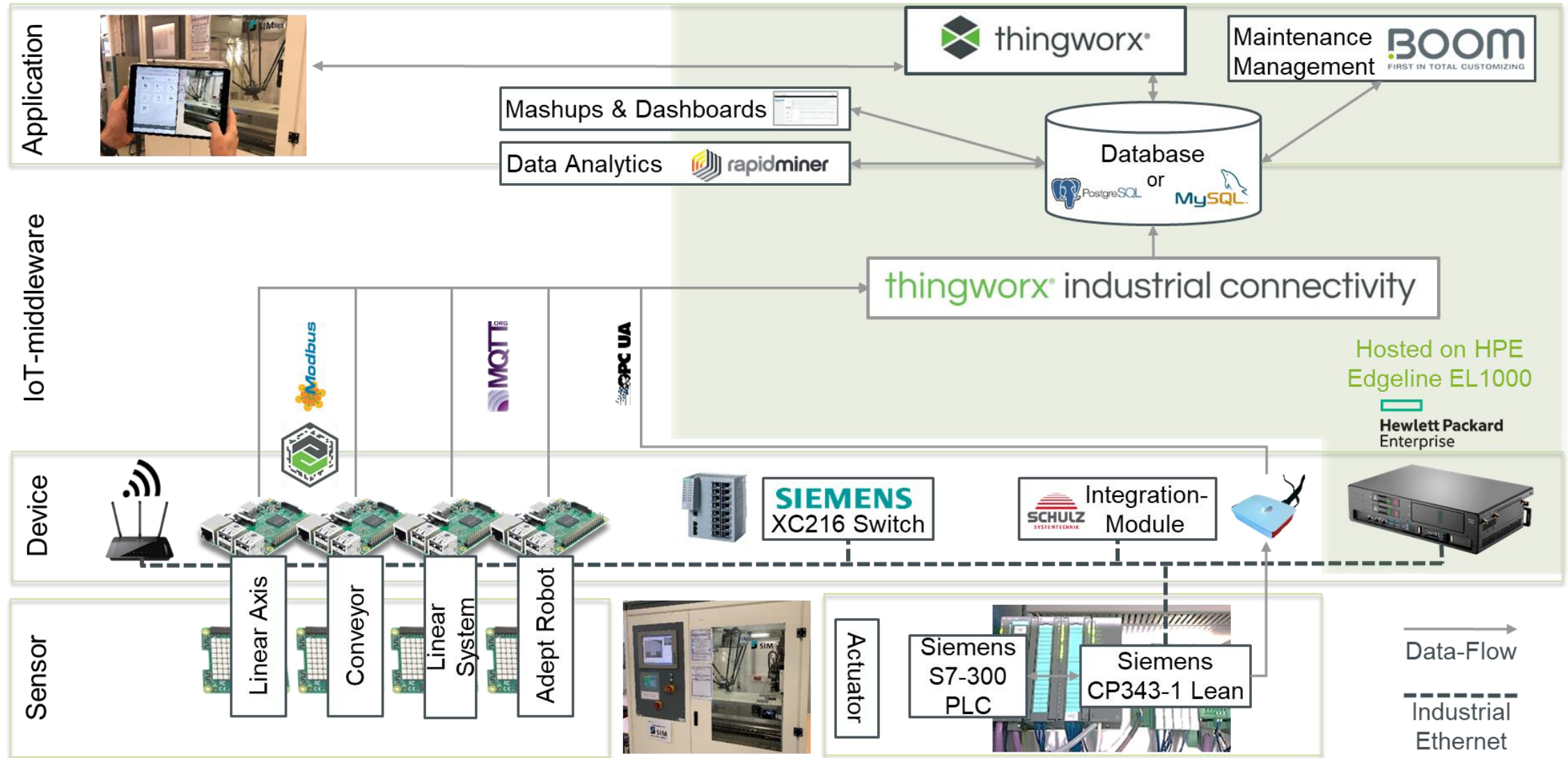
SEW-AC-Elektromotor-betriebenes Förderband



1

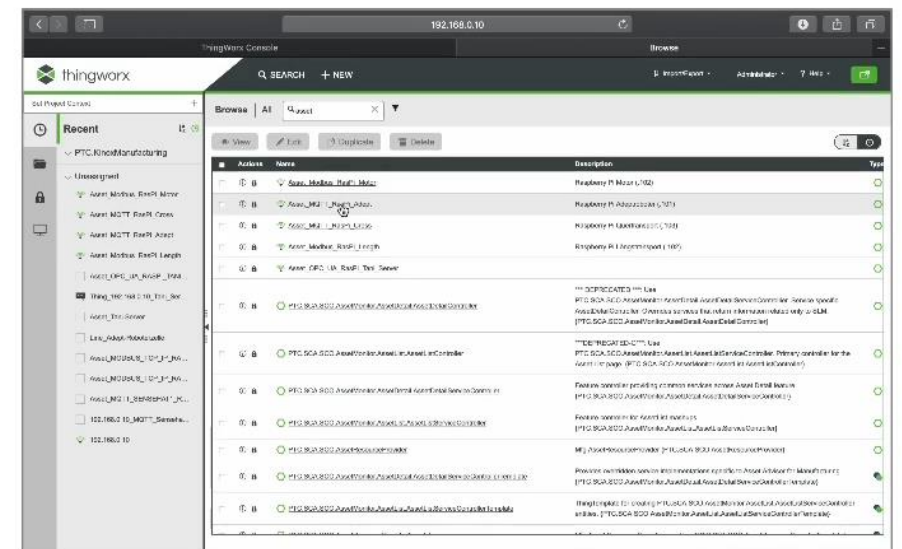
Adept-Quattro S650





Institute of Production Systems

Line & Asset-Setup



Architecture Levels	Implementation Options (examples only)						
Integration into Business Processes, eg. ERP	Grafana	Tableau	Siemens Mindsphere	Integration in MES	Splunk	Manufacturing Apps	PTC ThingWorx (<i>Manufacturing Apps</i>)
Data Analytics	RapidMiner	Python, R		MatLAB Statistics.		Microsoft Azure	PTC ThingWorx (<i>Industrial IoT Platform</i>)
Data Aggregation				Node-RED			
Data Storage	Relational DB (e.g. InfluxDB)	Hadoop-Cluster		Bosch IoT Cloud	Edge Server		PTC ThingWorx (<i>KEPServerEX</i>)
Interface Embedded System-Data Storage (Protocol)	MQTT	AMQP	OPC-UA	TCP/IP	LoRaWAN	HTTP	Modbus
Interface Embedded System-Data Storage (Network)	WLAN	LAN	BLE (Bluetooth)	5G	NFC	6LoWPAN	ZigBee
Local Data ETL and Pre-processing (Software)	Node-RED	RapidMiner	R & Python	Siemens Simatic Software	Bosch XDK, Bosch Connected Industrial Sensor Solution (CISS)	Microsoft Azure IoT-Edge	PTC ThingWorx
Local Data ETL and Pre-processing (Hardware)	Raspberry Pi Banana Pi	Harting Mica	Balluf IO Link	MindConnect 2040		PLC (e.g. Simatic S7-1500)	...
Interface Embedded System-Sensors	RS-485	I²C	CAN-Bus	SPI-Bus			RS-232
Sensors	Raspberry Sense Hat	External Sensors	Internal Sensors	Bosch Phantom	

